



Belt Driven high speed automation modules

For high speed automation, both gantry and articulated arm robots are widely used throughout industry. Because of the many inherent advantages of the gantry robot, it is a solid choice for: palletizing, storage and retrieval, machine loading, parts transfer, material handling, automated assembly. Parker offers numerous standard gantry configurations as well thousands of configured product options to develop a customer specific system solution to solve these and other automation applications. Utilization of these pre-engineered systems enables the user to redirect scarce engineering resources from motion system design to machine or process functionality.

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Parker's family of linear modules provides the most comprehensive line of high throughput linear positioning devices in the industry. These electromechanical positioners are designed to shuttle a payload at high speeds to multiple locations along a linear travel path. They serve as the primary building blocks for Parker pre-engineered gantry systems or customer designed automation systems. Parker linear modules are offered in several unique product families which can address a broad range of travel, speed, load, accuracy, and environmental requirements. There are three bearing systems (polyamide roller, steel roller, or square rail), three drive types (belt-and-pulley or rack-and-pinion, or linear servo motor), and up to six different cross sectional sizes (60, 80, 100, 120, 150 and 180 mm) from which to choose. Systems designed around these elements have effectively, efficiently, and economically satisfied the widest range of application requirements for high speed automation.

HPLA Series

Page 200-213



The next generation of belt driven modules, the HPLA expands on the roller wheel bearing design with the addition of high-load capacity steel wheels. The steel wheels significantly increase normal and moment load capacities of this belt driven actuator.

- Travel Range: 9.0 meters
- Load Capacity: 1530 kg
- Maximum Speed: 5 meters/sec.
- Duty Cycle: 100%
- Repeatability: ± 0.2 mm

HLE-RB Series

Page 214-227



These are the most popular electromechanical modules in the Parker line. They utilize a unique composite roller wheel bearing design coupled with a timing belt and pulley drive mechanism to provide long travel with high speed and high acceleration.

- Travel Range: 7.9 meters
- Load Capacity: 600 kg
- Maximum Speed: 5 meters/sec.
- Duty Cycle: 100%
- Repeatability: ± 0.2 mm

HLE-SR Series

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The "SR" series, having a square rail ball bearing system, complement the RB series by providing increased moment load capacities without an increase in profile size. The SR utilizes the same reliable timing belt and pulley drive system found in the RB.

- Travel Range: 6.0 meters
- Load Capacity: 600 kg
- Maximum Speed: 3 meters/sec.
- Duty Cycle: 100%
- Repeatability: ± 0.2 mm

HLE-Z Series

Page 240-245



The “endless” linear unit is designed for positioning payloads over long travel distances with high rigidity and repeatability. This is accomplished by incorporating Parker’s uniquely designed rack-and-pinion based drive system with the RB series roller wheel bearing system.

- Travel Range: 50 meters
- Load Capacity: 600 kg
- Maximum Speed: 5 meters/sec.
- Duty Cycle: 100%
- Repeatability: ± 0.05 mm

HZR Series

Page 246-251

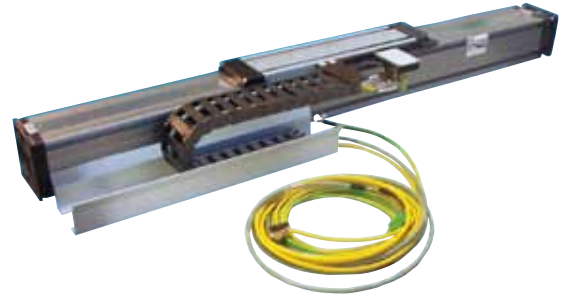


The HZR is a vertical unit specifically designed to meet the high speed and force requirements of the automation industry. The fixed housing and movable aluminum extrusion permit the unit to retract out of the work area, thereby keeping the work area free of obstructions.

- Travel Range: 2.0 meters
- Load Capacity: 150 kg
- Maximum Speed: 5 meters/sec.
- Duty Cycle: 100%
- Repeatability: ± 0.2 mm

BLMA Series

Page 252-253



The BLMA is a plug and play linear motor actuator which houses a powerful linear servo motor (386 pounds of peak thrust) in a high strength rigid aluminum body to enable high end performance with highly repeatable positioning over long unsupported spans.

- Travel Range: 6.0 meters
- Load Capacity: 700 kg
- Maximum Speed: 7 meters/sec.
- Duty Cycle: 100%
- Repeatability: ± 0.01 mm

Gantry Systems

Page 254-269

Parker's gantry systems provide cost-effective, easy to integrate solutions that satisfy the vast majority of automation requirements. In addition to these standard gantry systems, Parker offers products with additional capabilities to fulfill the needs of special applications. Our engineering skill and manufacturing expertise have integrated these products into custom-tailored gantry solutions which have successfully addressed the most unique and exacting requirements of machine builders and integrators around the world.



Support Structures

Page 270

Parker can include the support structure and machine guarding as part of your complete system solution. Parker's ParFrame™ extruded aluminum structures are suited for light to medium duty requirements. High strength steel supports are offered for applications involving greater loads and forces.



Motors, Drives, and Controls (Electrical Subsystems)

Page 271

A high speed multi-axis Gantry Robot requires a complete electromechanical solution where the machine Interface, Control and Motor/Drive functions are seamlessly integrated with the mechanical elements. Parker's wide range of electrical products and subsystems enable Gantry Robots to be supplied to the customer at the level of integration most suitable for his need. Whether you need a basic mechanical unit, a unit including drives and motors, or a full-blown electromechanical system ready to run or link to a PLC, Parker has the best solution.



Additional Capabilities

Page 277-280



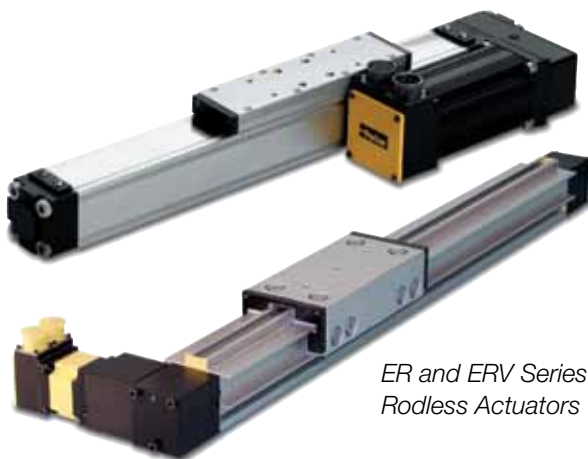
HDM Series Rotary Motion Modules



ET Series Rod Style Electric Cylinders



HTR Telescopic Vertical Units



*ER and ERV Series
Rodless Actuators*



**Belt Driven
Tables**



*LCB Series Compact
Rodless Actuators*

HPLA Series Belt Driven Linear Modules

Features

- Strong – steel roller bearing option for highest load capacity – 1530 kg
- Rugged construction for heavy duty applications
- Thrust force capacity to 5455 N
- Standard travel up to 9 meters
- Velocity up to 5 meters/sec.
- Positional repeatability of ± 0.2 mm
- Timing belt and pulley drive mechanism for fast, accurate positioning

The Modular Concept

Provides the ideal solution for applications:

Modular drive system:

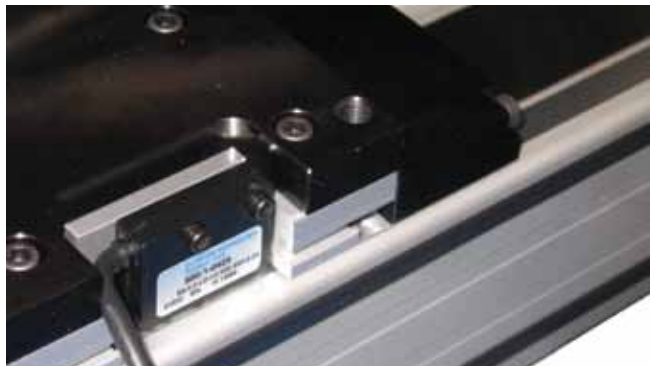
- Increased system stiffness due to larger belt width
- Low maintenance
- High performance due to hollow shaft input

Modular guide system:

- Provides an alternative to composite wheel material
- Quiet operation
- Low maintenance
- Steel wheel option on an integrated steel rolling surface for increased load capacity
- High load-bearing capacity
- High levels of rigidity

Various options for adaptation to wide ranging applications:

- Steel cover strip
- Corrosion-resistant stainless steel version for application in clean rooms or in the food industry
- Integrated position feedback system for maximum precision
- Optional IP30 rated strip seal



HPLA Encoder Option

See pages 272-276 for available options and accessories.



Proven Technology

- Direct mounting for planetary gear reducers – eliminating complexity of additional machined parts or couplings
- Adjustable “end of travel” limit switches and “Home” position sensor
- Cable carrier systems
- Performance matched Parker servo systems
- Structural components for vertical and multi-axis mounting
- Toe clamps and hardware for fast/easy mounting
- External bumper option
- Link shafts and support bearing for dual unit axes
- Splice plates for extending travels beyond length available in a single profile

Typical Fields of Application

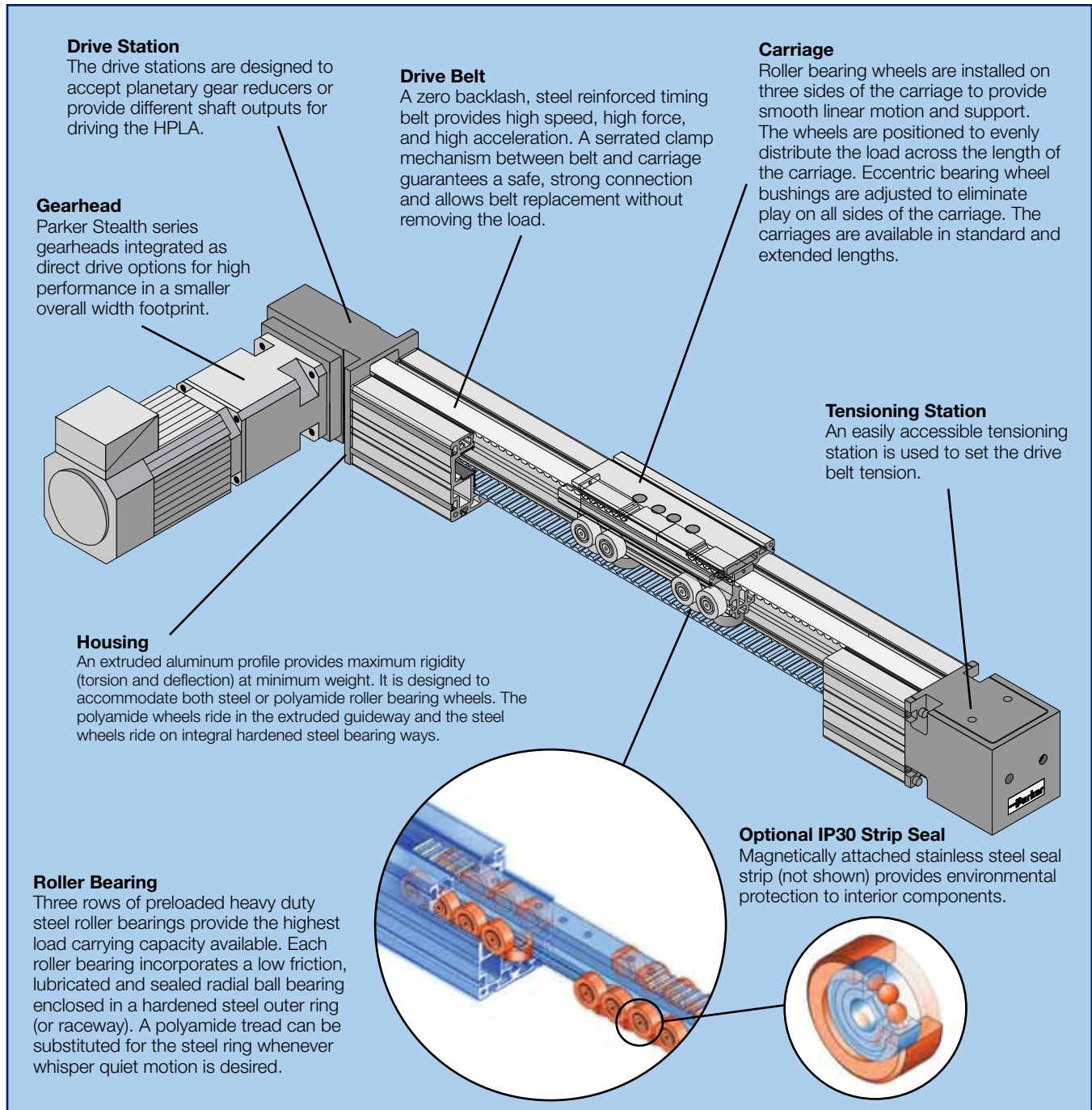
As part of advanced, cost-effective construction of machines and handling systems:

- Materials handling: palletizing, depalletizing, feeding, part removal
- Cleanroom technology: wafer transport, wafer coating
- Warehouse technology: parts picking, storage and retrieval
- Machine tool automation: workpiece loading and unloading, tool changing
- Construction: formwork, placing reinforcing steel bars in concrete
- Process engineering: painting, coating, bonding
- Testing technology: guiding ultrasonic sensors, laboratory equipment
- Textile machinery building: cross-cutting, slitting and stacking, quilting, seam stitching



The HPLA is a rugged “next generation” linear module that offers high speed, high acceleration, and long travel, combined with stiff, rigid construction characteristics. It is ideally suited as a single axis product or as a component for high speed multi-axis gantries. The HPLA carriage is rigidly supported on three sides by heavy duty roller bearings, housed in a rugged aluminum housing. The bearing wheels are pre-loaded via eccentric bushings to eliminate play in the system, and are strategically located to evenly distribute the load across the length of the carriage.

A high strength steel reinforced drive belt and pulley system provides fast and highly repeatable positioning of the carriage. This high thrust drive belt is securely connected to the carriage by a unique clamping system. This system provides a secure connection and enables easy belt replacement without the need to remove the payload. Having a low coefficient of friction, the carriage design provides a high mechanical efficiency and long service life. Special carriage lengths and linear units with multiple carriages are available for custom applications.



HPLA Series Specifications

		HPLA80		HPLA120		HPLA180		HPLA180 (Rack Drive)
Characteristic	Units	Polyamide Wheel	Steel Wheel	Polyamide Wheel	Steel Wheel	Polyamide Wheel	Steel Wheel	Polyamide Wheel
Unit Weight (basic unit without stroke)								
Standard Carriage, NL	kg (lb)	6.8 (15.0)	7.5 (16.5)	20.2 (44.4)	21.6 (47.5)	57.2 (125.8)	61.6 (135.3)	78.4 (172.5)
Extended Carriage, VL	kg (lb)	8.6 (18.9)	9.5 (20.9)	25.2 (55.4)	27.1 (59.6)	74.8 (164.6)	80.9 (178.0)	95.2 (209.4)
Carriage Weight								
Standard Carriage, NL	kg (lb)	1.7 (3.7)	1.8 (4.0)	5.8 (12.8)	6.0 (13.2)	12.3 (27.1)	12.6 (27.7)	32.5 (71.5) ⁽¹⁾
Extended Carriage, VL	kg (lb)	2.6 (5.7)	2.8 (6.2)	8.8 (19.4)	9.2 (20.2)	21.1 (46.4)	21.8 (48.0)	39.8 (87.6) ⁽¹⁾
Weight/Meter of Additional Travel	kg/m (lb/ft)	6.1 (4.1)	7.3 (4.9)	13.7 (9.2)	15.5 (10.4)	29.4 (19.8)	33.6 (22.6)	31.5 (21.2)
Moment of Inertia (related to the drive shaft)								
Standard Carriage, NL	kg-cm ² (lb-in ²)	17.8 (6.1)	18.4 (6.3)	142 (48)	146 (50)	725 (247)	743 (253)	698 (238)
Extended Carriage, VL	kg-cm ² (lb-in ²)	25.4 (8.7)	26.5 (9.0)	197 (67)	204 (70)	1121 (382)	1154 (393)	845 (288)
Travel and Speed								
Maximum Speed ⁽²⁾	m/s (in/s)	5 (200)		5 (200)		5 (200)		5 (200)
Maximum Acceleration ⁽²⁾	m/s ² (in/s ²)	10 (393)		10 (393)		10 (393)		10 (393)
Max. Travel, Standard Carriage NL ⁽³⁾	mm (in)	5540 (218)	5520 (217)	9470 (372)	9440 (371)	9240 (363)	9200 (362)	8680 (341)
Max. Travel, Extended Carriage VL ⁽³⁾	mm (in)	5390 (212)	5370 (211)	9270 (365)	9240 (363)	8940 (352)	8900 (350)	8380 (330)
Geometric Data								
Cross Section, Square	mm (in)	80 (3.15)		120 (4.72)		180 (7.09)		180 (7.09)
Moment of Inertia I _x	cm ⁴ (in ⁴)	139 (3.34)		724 (17.39)		3610 (86.73)		3610 (86.73)
Moment of Inertia I _y	cm ⁴ (in ⁴)	165 (3.96)		830 (19.94)		4077 (97.95)		4077 (97.95)
Moment of Elasticity	N/mm ² (lb/in ²)	0.72 x 10 ⁵ (0.1044 x 10 ⁶)		0.72 x 10 ⁵ (0.1044 x 10 ⁶)		0.72 x 10 ⁵ (0.1044 x 10 ⁶)		0.72 x 10 ⁵ (0.1044 x 10 ⁶)
Pulley Data, Torques, Forces								
Travel Distance per Revolution	mm/rev (in/rev)	180 (709)		270 (10.63)		420 (16.54)		280 (11.02)
Response Radius of Drive Pulley	mm (in)	28.7 (1.13)		43.0 (1.69)		66.8 (2.63)		44.6 (1.75)
Maximum Drive Torque	Nm (lb-in)	47.4 (420)		131.4 (1165)		368 (3264)		58 (514)
Maximum Belt Traction (effective load)				Refer to charts on following pages				
Repeatability ⁽³⁾⁽⁴⁾	mm (in)	± 0.2 (± 0.008)		± 0.2 (± 0.008)		± 0.2 (± 0.008)		± 0.05 (± 0.002)

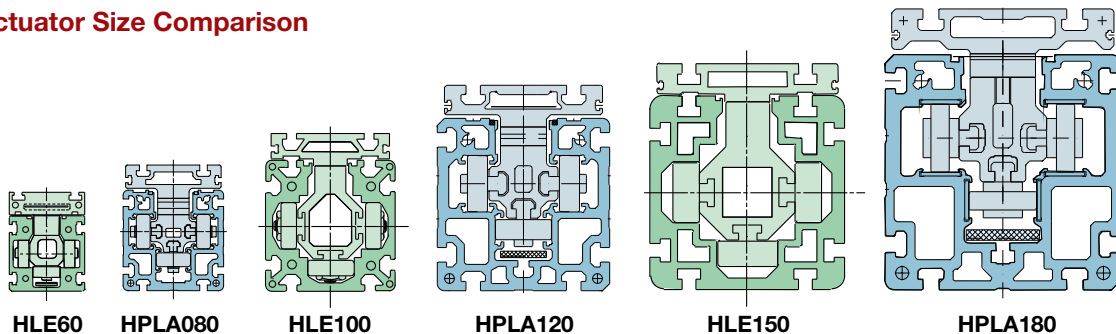
(1) Includes weight of drive module.

(2) Greater speeds and accelerations may be achieved.

(3) Bumper to bumper maximum stroke - splicing possible for longer travel distances including safety zone.

(4) Nominal value - component dependent. For improved repeatability consult factory.

Linear Actuator Size Comparison



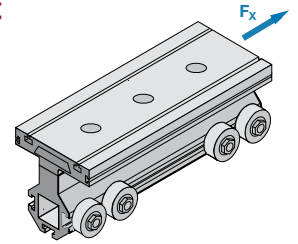


HPLA080 Series – Load-Bearing Capacity of Carriage and Timing Belt

Load-Bearing Capacity of HPLA080 Timing Belt (F_x)

Description	Gearhead	Drive Option	Transferable Thrust Force (n)	
			Nominal Belt Tension (81,000 km life)	Maximum Belt Tension (46,000 km life)
Unsupported Pulley	PX90/PV90	S01/S02	500	625
	PS90	S01/S02	675	900
Supported Pulley	PX90/PX115 PV90/PV115 PS90	S03/S04/ S08/S09	925	1115

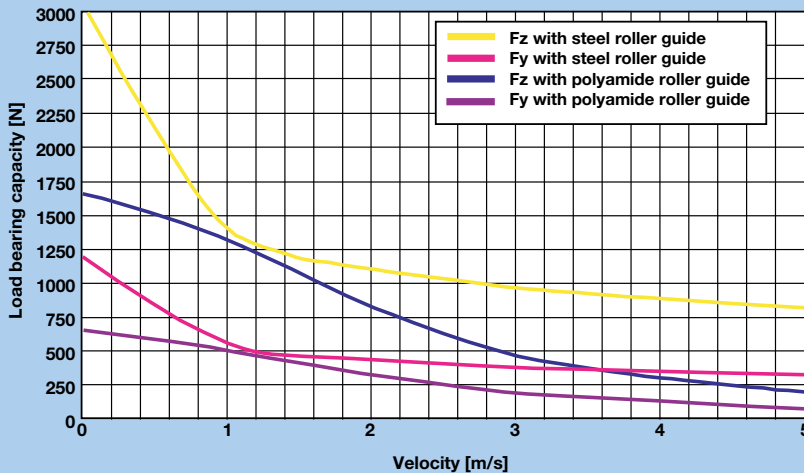
The forces and moments that the carriage is capable of transferring are speed-dependent. The



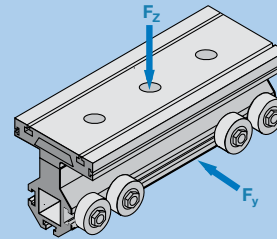
curves shown in the graphs apply to a standard carriage (S). With the extended carriage (E), all the values apart from F_x (load-bearing capacity of timing belt) can be doubled if the load is applied equally to both halves of the carriage or distributed uniformly along its entire length.

HPLA080 Load-Bearing Capacity (F_y and F_z)

(Values double for extended carriage)

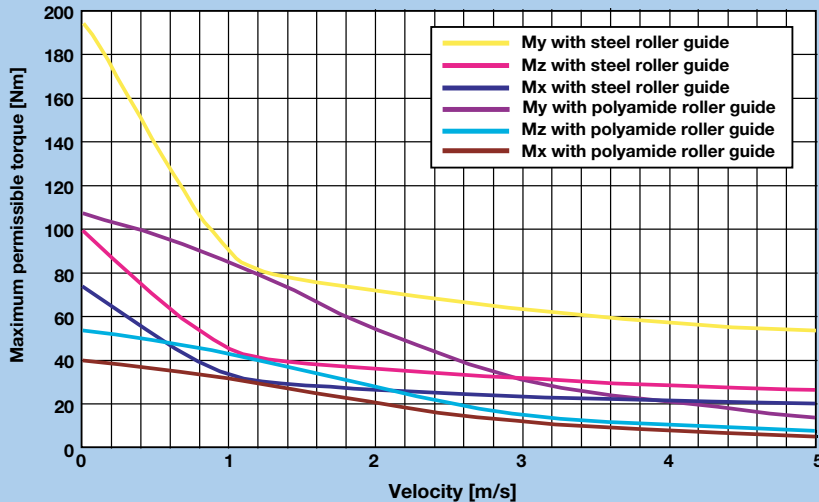


The curves show the maximum load-bearing capacity of a carriage in one direction of force or torque. If several loads are applied in different directions, the values given by the curves must be derated, i.e. the load or speed should be reduced if necessary.



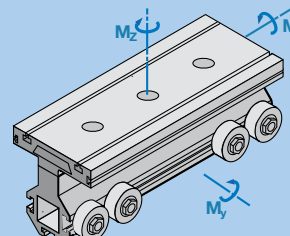
HPLA080 Maximum Permissible Moment Load (M_x , M_y and M_z)

(Values double for extended carriage)



“DimAxes” software is available for determination of precise carriage loading.

Visit www.parkermotion.com to request a Gantry Robot CD.

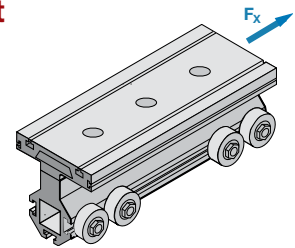


HPLA120 Series – Load-Bearing Capacity of Carriage and Timing Belt

Load-Bearing Capacity of HPLA120 Timing Belt (F_x)

Description	Gearhead	Drive Option	Transferable Thrust Force (n)	
			Nominal Belt Tension (81,000 km life)	Maximum Belt Tension (46,000 km life)
Unsupported Pulley	PV115/PX115	S01/S02	675	900
	PS115	S01/S02	1515	2015
Supported Pulley	PV115 PX115 PS90/PS115	S03/S04/ S08/ S09	1700	2235

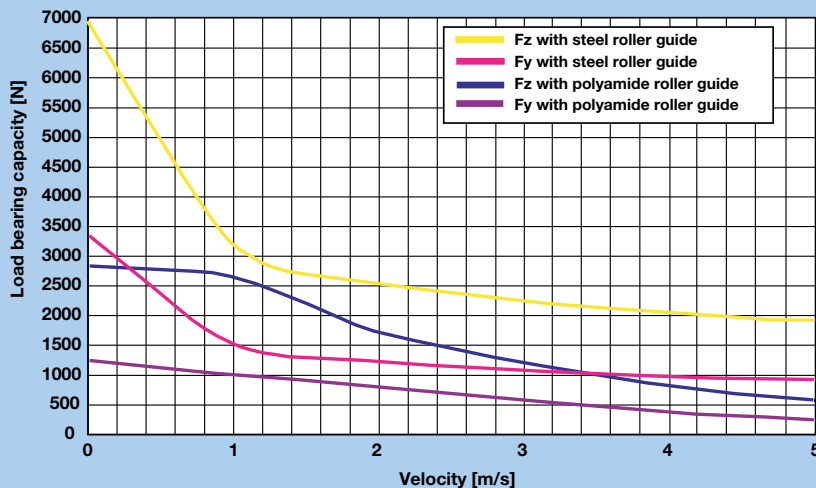
The forces and moments that the carriage is capable of transferring are speed-dependent. The



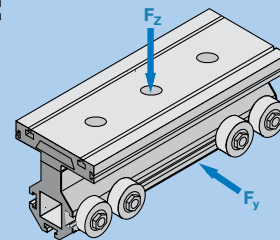
curves shown in the graphs apply to a standard carriage (S). With the extended carriage (E), all the values apart from F_x (load-bearing capacity of timing belt) can be doubled if the load is applied equally to both halves of the carriage or distributed uniformly along its entire length.

HPLA120 Load-Bearing Capacity (F_y and F_z)

(Values double for extended carriage)



The curves show the maximum load-bearing capacity of a carriage in one direction of force or torque. If several loads are applied in different directions, the values given by the curves must be derated, i.e. the load or speed should be reduced if necessary.

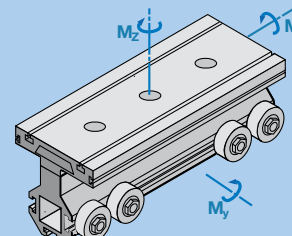
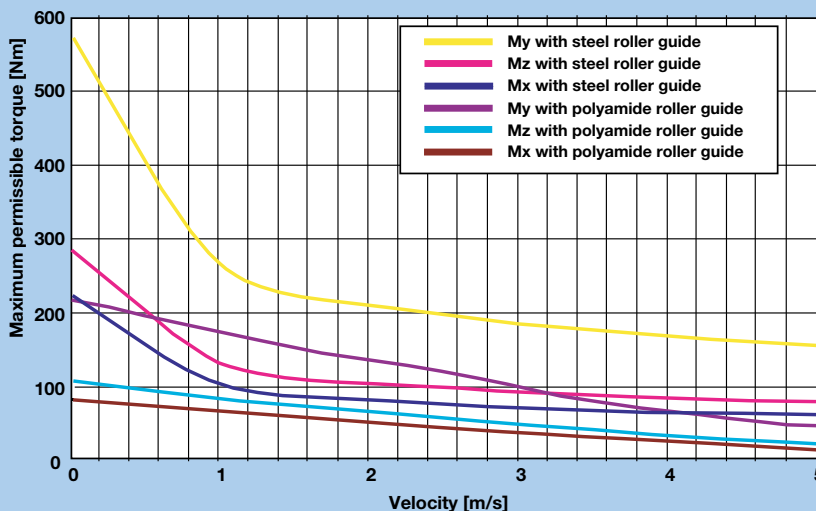


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HPLA120 Maximum Permissible Moment Load (M_x , M_y and M_z)

(Values double for extended carriage)



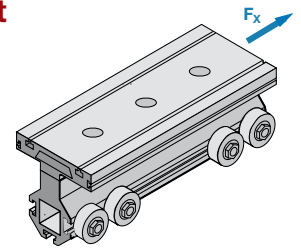


HPLA180 Series – Load-Bearing Capacity of Carriage and Timing Belt

Load-Bearing Capacity of HPLA180 Timing Belt (F_x)

Description	Gearhead	Drive Option	Transferable Thrust Force (n)	
			Nominal Belt Tension (81,000 km life)	Maximum Belt Tension (46,000 km life)
Unsupported Pulley	PS142	S01/S02	1405	1804
Supported Pulley	PS115 PS142	S03/S04/ S08/S09	4170	5455

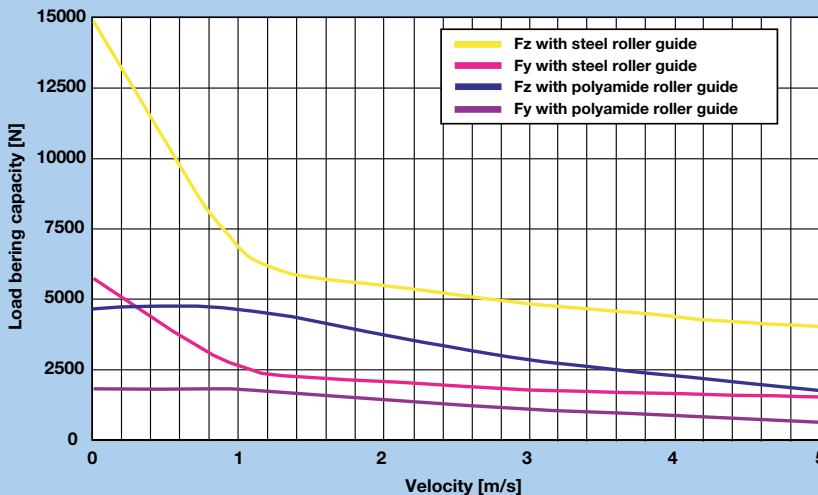
The forces and moments that the carriage is capable of transferring are speed-dependent. The



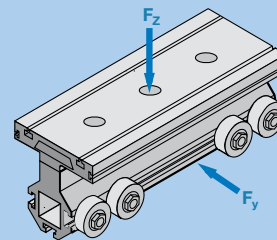
curves shown in the graphs apply to a standard carriage (S). With the extended carriage (E), all the values apart from F_x (load-bearing capacity of timing belt) can be doubled if the load is applied equally to both halves of the carriage or distributed uniformly along its entire length.

HPLA180 Load-Bearing Capacity (F_y and F_z)

(Values double for extended carriage)

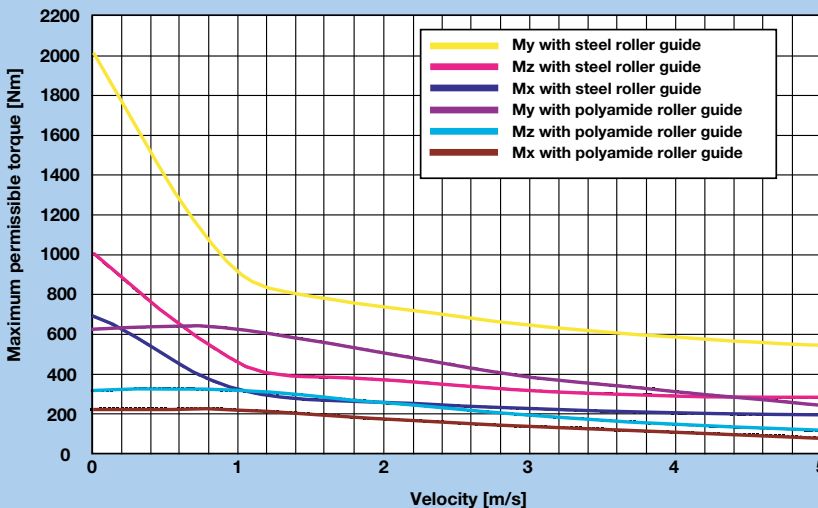


The curves show the maximum load-bearing capacity of a carriage in one direction of force or torque. If several loads are applied in different directions, the values given by the curves must be derated, i.e. the load or speed should be reduced if necessary.



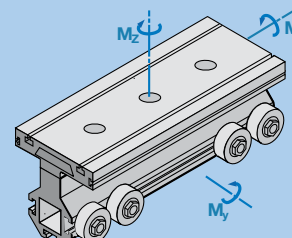
HPLA180 Maximum Permissible Moment Load (M_x , M_y and M_z)

(Values double for extended carriage)



“DimAxes” software is available for determination of precise carriage loading.

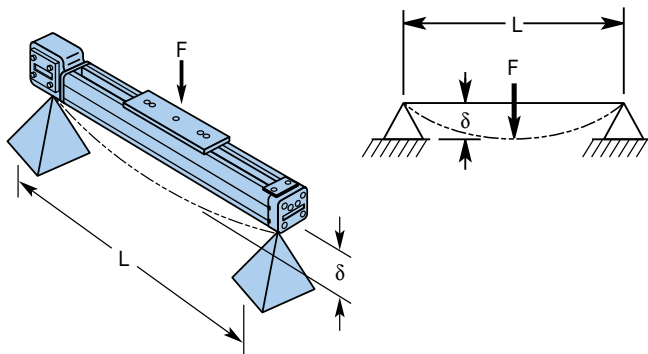
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HPLA Characteristics

The HPLA deflection curves can be used for determining the deflection based on the profile length and the application load weight. Applications requiring high acceleration forces can place a severe strain on the system stability. In these cases, a solid substructure may be required with the HPLA product being supported at frequent intervals.

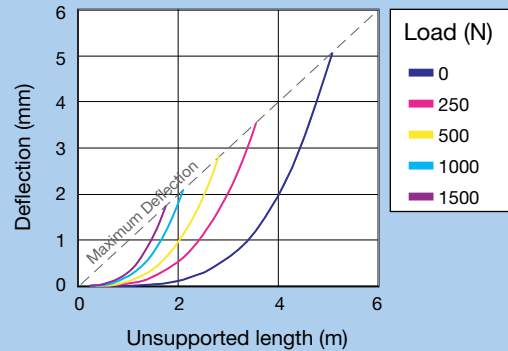
These deflection curves illustrate the deflection δ , based on the HPLA profile being simply supported at both ends. The graphs take into consideration the self deflection due to the weight of the profile, along with the load to be transported. The maximum deflection cannot be exceeded. If the maximum deflection is exceeded based on your application parameters, then additional supports are required. Alternatively, the next larger profile size may be considered. For deflection formulas and calculations, please refer to the Technical Information Library found on our web site: www.parkermotion.com



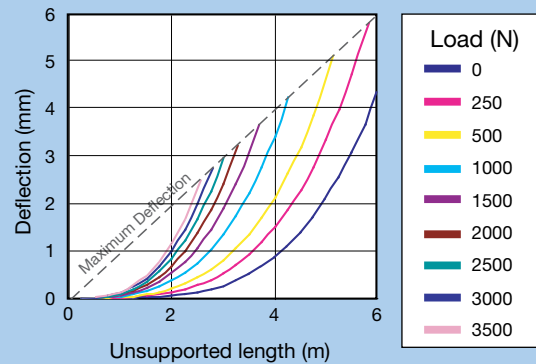
F = Force N
L = Unsupported length mm
 δ = Deflection mm

Deflection Curves

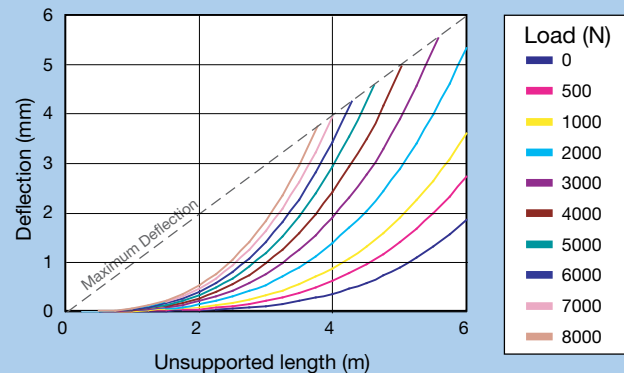
HPLA080



HPLA120



HPLA180





Dual Axis Considerations

When two parallel linear modules are required to form a single axis, the span or distance between each unit determines which type of shaft connection is required. In some cases, a link shaft support bearing might also be required.

Figure A

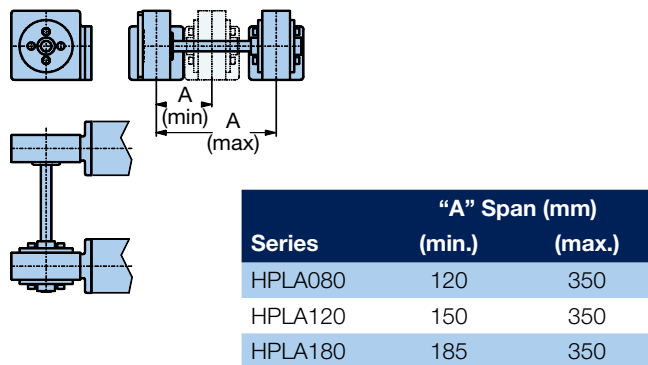


Figure B

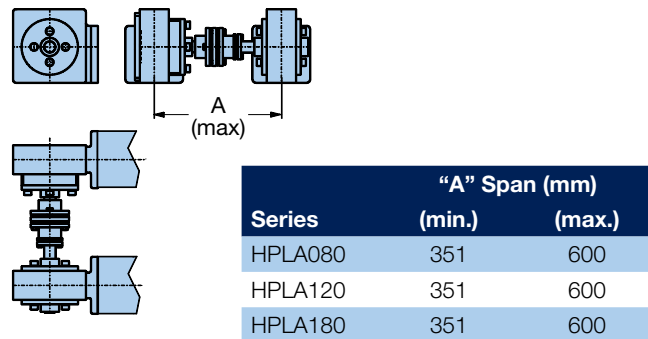
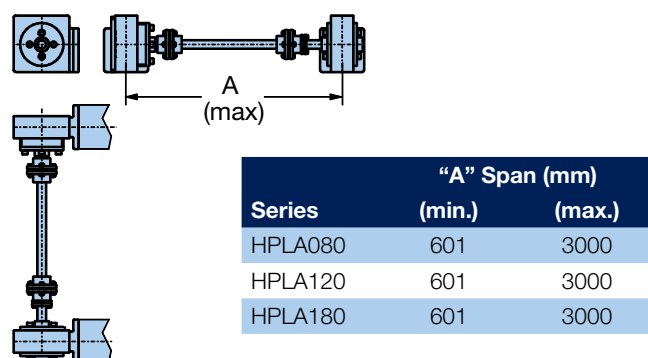
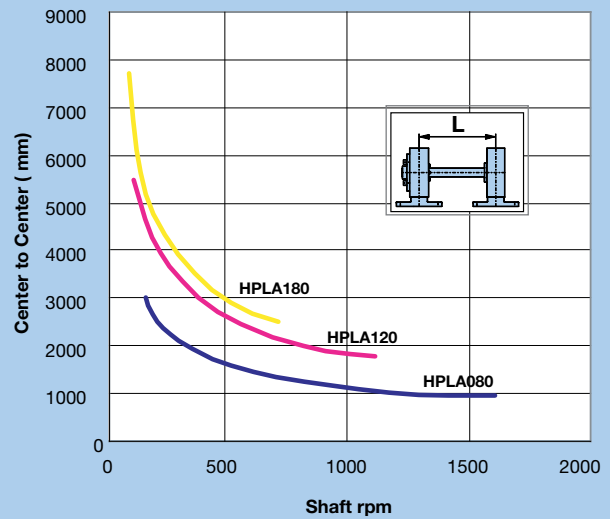


Figure C

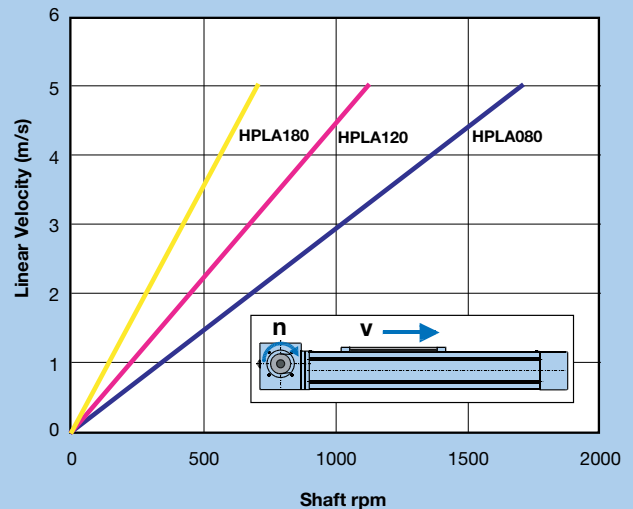


The link shaft bearing is used to support the linking shaft of an HPLA dual axis when there is a large center to center distance. This bearing must be used if the critical speed is exceeded with the dual-axis link shaft.

Critical Speed

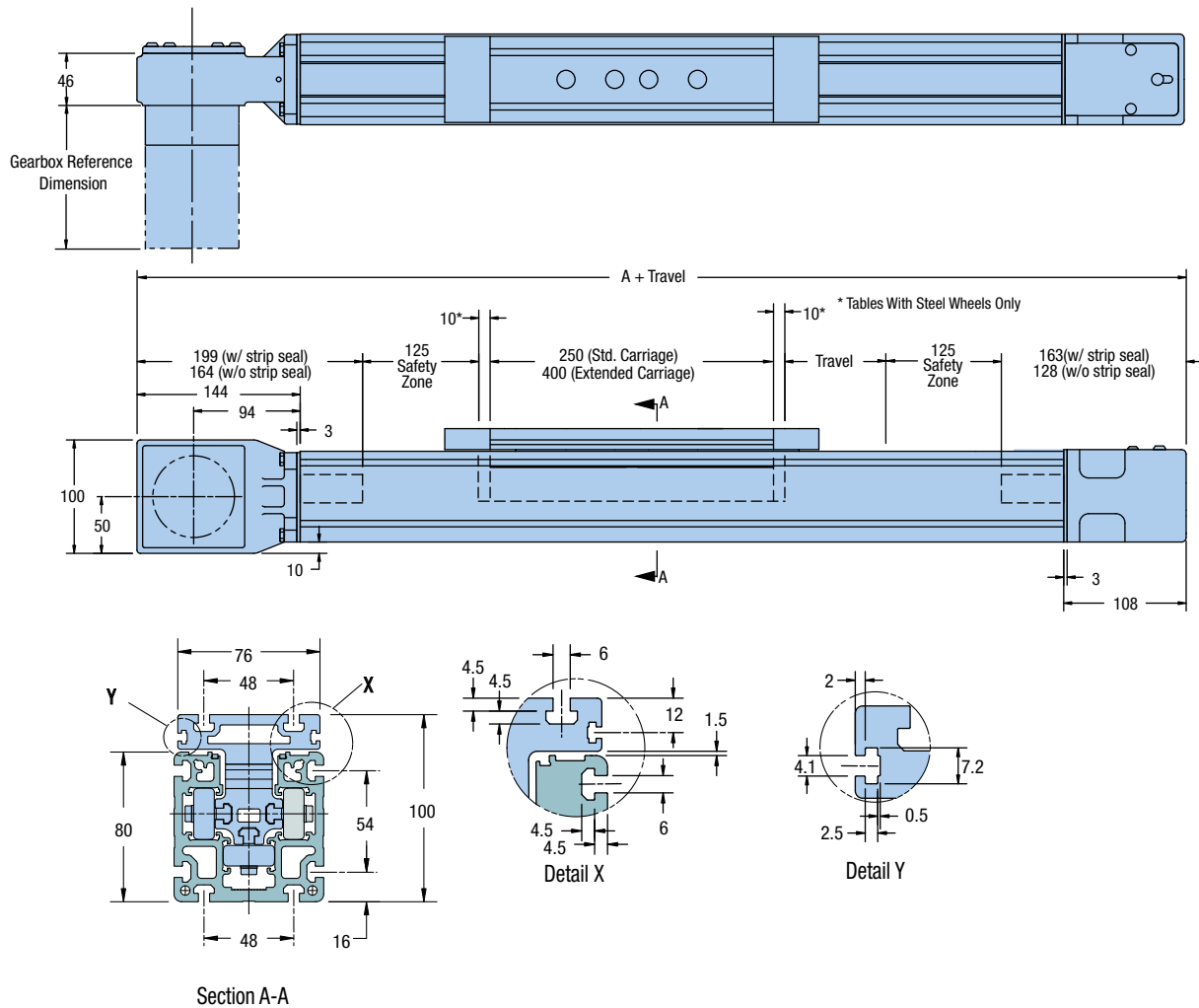


Linear Velocity



HPLA080 Drive Unit

Dimensions (mm)

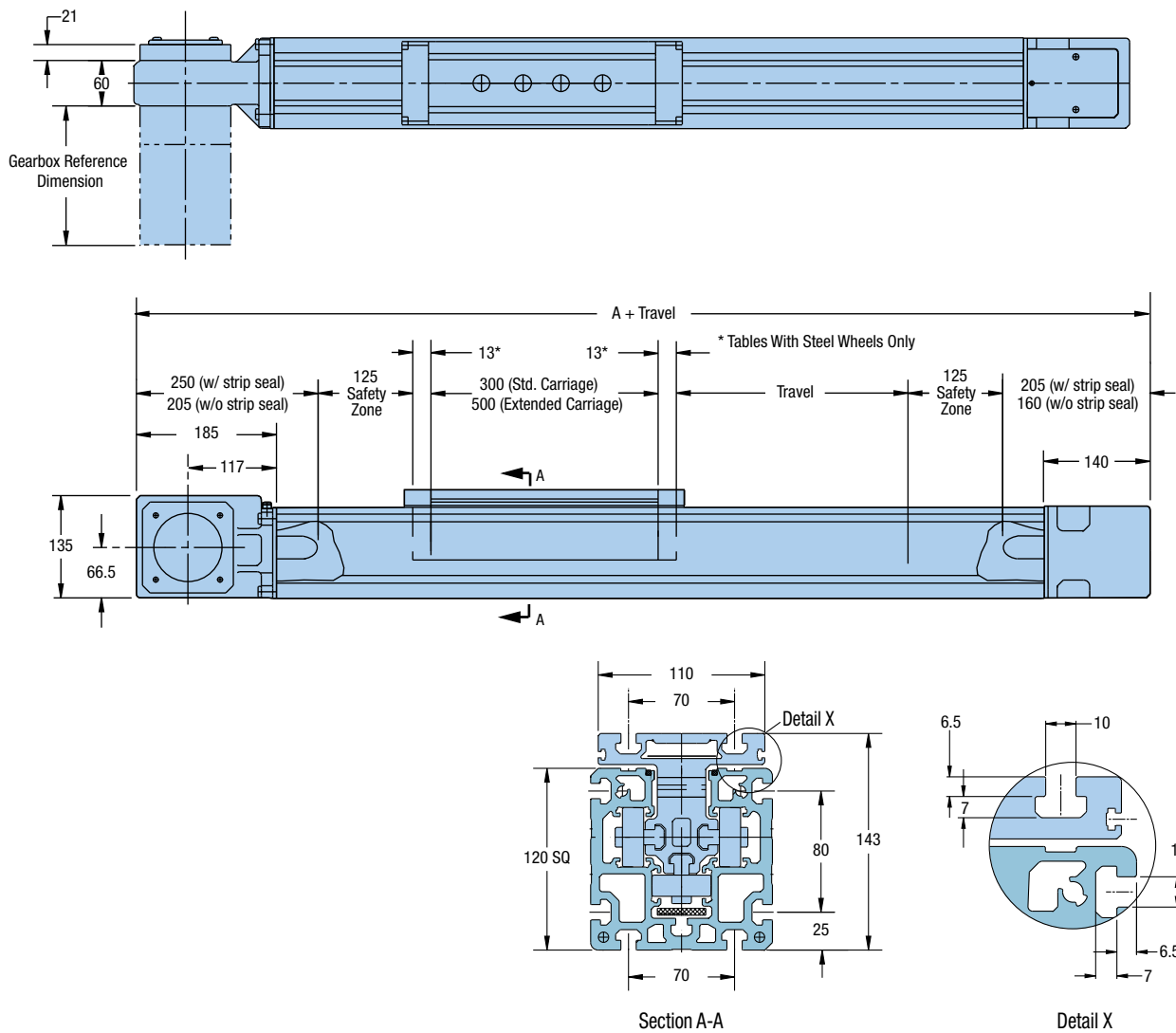


Description	Dimension A (mm)	
	With Strip Seal	Without Strip Seal
Standard Carriage - Polyamide Wheels	862	792
Standard Carriage - Steel Wheels	882	812
Extended Carriage - Polyamide Wheels	1012	942
Extended Carriage - Steel Wheels	1032	962



HPLA120 Drive Unit

Dimensions (mm)

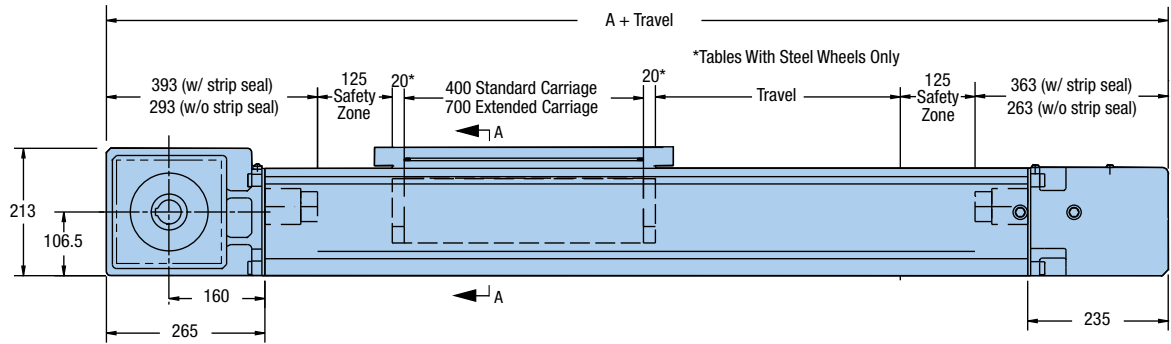
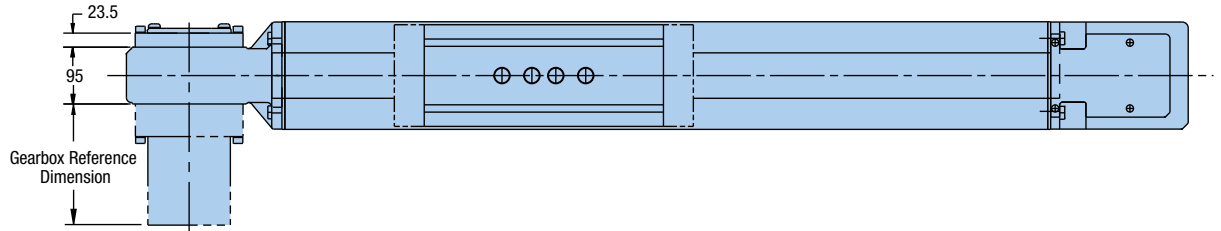


Belt Driven
Tables

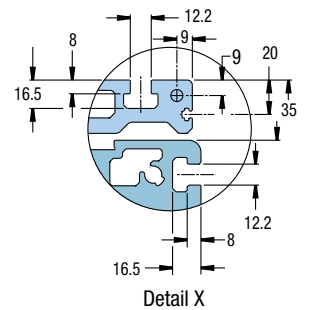
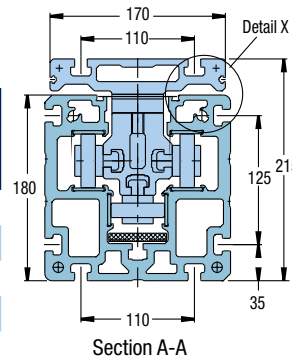
Description	Dimension A (mm)	
	With Strip Seal	Without Strip Seal
Standard Carriage - Polyamide Wheels	1005	915
Standard Carriage - Steel Wheels	1031	941
Extended Carriage - Polyamide Wheels	1205	1115
Extended Carriage - Steel Wheels	1231	1141

HPLA180 Drive Unit

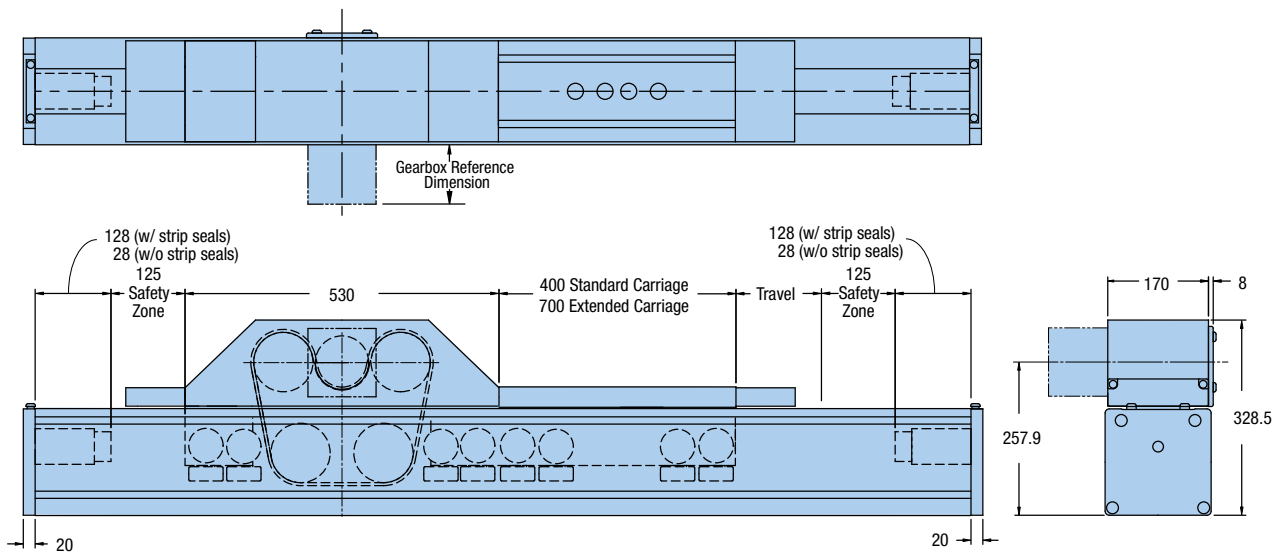
Dimensions (mm)



Description	Dimension A (mm)	
	With Strip Seal	Without Strip Seal
Standard Carriage - Polyamide Wheels	1408	1206
Standard Carriage - Steel Wheels	1446	1246
Extended Carriage - Polyamide Wheels	1706	1506
Extended Carriage - Steel Wheels	1746	1546



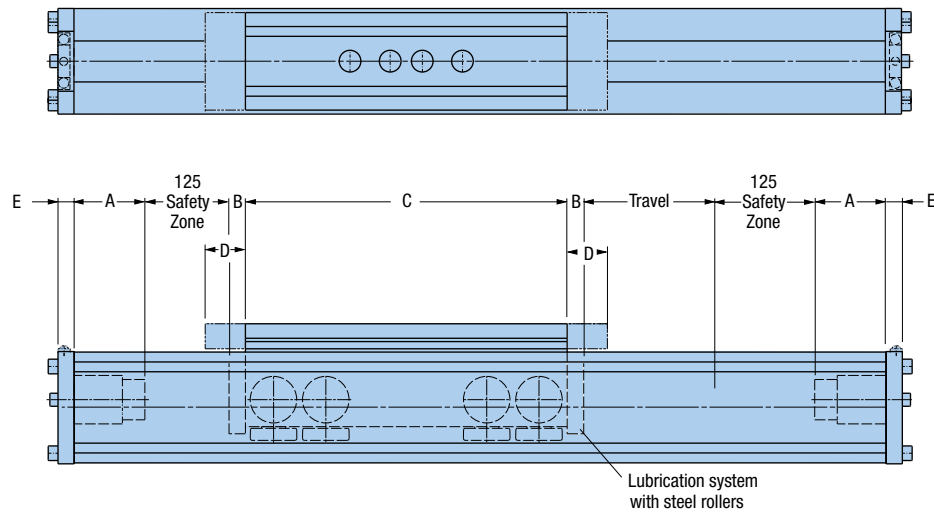
HPLA180 Rack Drive Unit





Idler Unit Dimensions

Dimensions (mm)



Series	Carriage Length	Wheel Type	Dimensions (mm)									
			With Strip Seal					Without Strip Seal				
			A	B	C	D	E	A	B	C	D	E
HPLA080	Standard	Polyamide	55	-	250	40	10	20	-	250	-	10
HPLA080	Extended	Polyamide	55	-	400	40	10	20	-	400	-	10
HPLA080	Standard	Steel	55	10	250	40	10	20	10	250	-	10
HPLA080	Extended	Steel	55	10	400	40	10	20	10	400	-	10
HPLA120	Standard	Polyamide	65	-	300	50	15	20	-	300	-	15
HPLA120	Extended	Polyamide	65	-	500	50	15	20	-	500	-	15
HPLA120	Standard	Steel	65	13	300	50	15	20	13	300	-	15
HPLA120	Extended	Steel	65	13	500	50	15	20	13	500	-	15
HPLA180	Standard	Polyamide	128	-	400	100	20	28	-	400	-	20
HPLA180	Extended	Polyamide	128	-	700	100	20	28	-	700	-	20
HPLA180	Standard	Steel	128	20	400	100	20	28	20	400	-	20
HPLA180	Extended	Steel	128	20	700	100	20	28	20	700	-	20

Belt Driven
Tables

Fill in an order code from each of the numbered fields to create a complete model order code.

① ② ③ ④ ⑤ ⑥ ⑦ ⑧ ⑨ ⑩ ⑪ ⑫ ⑬ ⑭ ⑮

Order Example: HPLA080 D1 B1 T2000 C1 DA1000 S08 F02 G2-05 K24 M98 R1 H1 LH1 E1

① Series

HPLA080
HPLA120
HPLA180

② Drive System

D0 Idler Unit
D1 Timing Belt Drive, Nominal Thrust, Maximum Life
D2 Timing Belt Drive, Maximum Thrust, Nominal Life
D9 Internal Rack and Pinion (HPLA180 only)

③ Bearing Option

B1 Polyamide Rollers
B2 Steel Rollers

④ Travel

Tnnnn Specified travel in mm (nnnn = mm)

⑤ Carriage

C1 Standard Length Carriage with Load Plate*
C2 Extended Length Carriage with Load Plate*
C3 Standard Length Carriage with Clamping Bar*
C4 Extended Length Carriage with Clamping Bar*

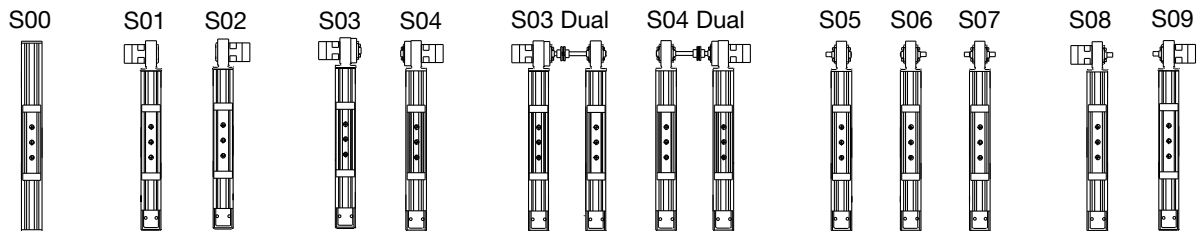
* See photos below.

⑥ Link Shaft Option

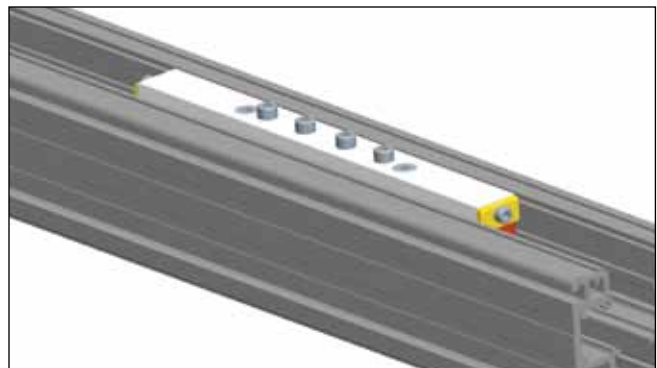
DA0000 No Link Shaft - Single Axis or Idler Unit
DAnnnn Double Unit, Specify Center to Center Distance (mm)

⑦ Drive Shaft Configuration

S00 No Shaft, Idler Unit
S01 Unsupported Pulley, Flange Left
S02 Unsupported Pulley, Flange Right
S03 Supported Pulley, Flange Left
S04 Supported Pulley, Flange Right
S05 Supported Pulley, Shaft Option, Left
S06 Supported Pulley, Shaft Option, Right
S07 Supported Pulley, Shaft Option, Both
S08 Supported Pulley, Flange Left, Shaft Right
S09 Supported Pulley, Flange Right, Shaft Left



Load Plate carriage option



Clamping Bar carriage option



⑧ Drive Housing Flange

F00	No Flange
F08	PV90/PX90 Flange (HPLA80 ONLY)
F09	PX115/PV115 Flange (HPLA080 and HPLA120 only)
F10	PS90 Flange (HPLA080 and HPLA120 only)
F11	PS115 Flange (HPLA120 & HPLA180 only)
F12	PS142 Flange (HPLA180 only)

⑨ Gearbox Option

G0-00	No Gearbox
G08-nn	PX90 Gearbox included
G09-nn	PX115 Gearbox included
G10-nn	PS90 Gearbox included
G11-nn	PS115 Gearbox included
G12-nn	PS142 Gearbox included
G14-nn	PV90 Gearbox included
G15-nn	PV115 Gearbox included

nn = ratio

Single stage ratios 3:1, 5:1, 10:1 Dual stage ratios 15:1, 25:1

⑩ Motor Kit Option

K00	No Flange
K20	NEMA23 stepper, 1/4" shaft
K21	BE23
K23	SMN60, MPM72 (metric), N070, J070
K24	SMN82, MPM89 (metric), N092, J092
K26	BE34
K34	MPP092x motor kit
K36	Parker MPP100/MPJ100
K39	Parker MPP115/MPJ115
K41	Parker MPP142/MPJ142
K50	Parker HDY55; MPL15XX (Allen Bradley)
K51	AKM3X-AN (Kollmorgen)
K52	SGMAH-04 (Yaskawa)
K53	SGMAH-08 (Yaskawa)
K54	MKD041 (Indramat)
K55	AKM4X-AN (Kollmorgen)
K56	MKD070 (Indramat)
K57	MKD090 (Indramat)

⑪ Motor Mount Option

M00	No Motor
M98	Mount Parker Motor
M99	Mount Customer Motor (Consult Factory)

⑫ Environmental Option

R1	Standard preparation with strip seal ¹
R2	Standard preparation with no strip seal
R3	Corrosion resistant preparation with strip seal ^{1, 2}
R4	Corrosion resistant preparation with no strip seal ²

¹ C1, C2 Carriage Load Plate Only

² B1 Bearing Option Polyamide Rollers Only

⑬ Mounting Orientation

H1	Carriage Up
H2	Carriage Down
H3	Carriage on Side, Drive Station Up
H4	Carriage on Side, Drive Station Down

⑭ Limit/Home Switch Option*

LH0	No Limit Switch Assembly
LH1	Three Mechanical Switches
LH2	Two Mechanical Switches, One Proximity (NPN)
LH3	Three NPN Prox Switches, 10-30 VDC
LH4	Three PNP Prox Switches, 10-30 VDC

*C1, C2 Carriage Load Plate Only

⑮ Linear Encoder

E1	Without Linear Encoder
E5	5.0 Micron Resolution, Magnetic Type
E7	Sine Cosine Output, Magnetic Type

*C1, C2 Carriage Load Plate Only